

①

Interrupts

Interrupt Routines are program segments which are executed when an interrupt source is activated.

PIE16f84 has the following interrupt sources

1) External hardware interrupt

RB0/INT is used as interrupt signal source

2) Software interrupt or internal interrupt.

when timer register TMRO makes a full count; i.e., counter (TMRO) starts from 0 counts upto FF and back to 0 again, a software interrupt or internal interrupt occurs.

3) PORTB bits RB4, RB5, RB6, RB7 can be used as hardware interrupt sources.

②

INTCON Register (Interrupt Control Register)

7	6	5	4	3	2	1	0
GIE	EEIE	TOIE	INTE	RBIE	TOIF	INTF	RBIF

GIE → Global Interrupt Enable bit

1 → Enables all unmasked interrupts

0 → Disables all interrupts

TOIE → TMR0 Overflow Interrupt Enable bit

1 → Enables the TMR0 interrupt

0 → Disables the TMR0 interrupt

INTE → RBO/INT External Interrupt Enable bit

1 → Enables the RBO/INT external interrupt

0 → Disables the RBO/INT external interrupt

INTF → RBO/INT External Interrupt Flag bit

1 → The RBO/INT external interrupt occurred

(must be cleared in software)

0 → The RBO/INT external interrupt did not occur

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When an interrupt signal is received the following set of events occur

- 1) Program counter value is saved into the stack register. That is, return address is placed on top of the stack.
- 2) Program counter is loaded by $0x04$ i.e, program execution goes with the command at address location $0x04$
- 3) At address $0x04$ goto interrupt-subroutine_{re} command is executed.
- 4) After execution of interrupt-subroutine PC is loaded by stack register value
- 5) Program execution goes from the point it stayed.

④

An assembly program with interrupt subroutine is written in general as

```
list P=16f84A
```

```
include "p16f84A.INC"
```

```
org 0x000;
```

```
goto main;
```

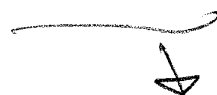
```
org 0x004;
```

```
goto interrupt-subroutine
```

```
main bsf INTCON, GIE; → Enable
```

```
bsf INTCON, INTE; Global
```

```
!
!
!
```



Interrupts

Enable RBO/INTP
interrupt
source

```
loop goto loop;
```

```
interrupt-subroutine
```

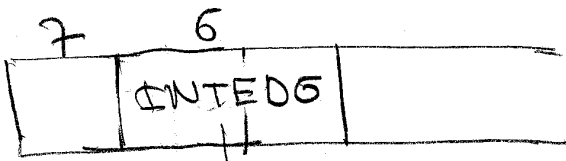
```
bcf INTCON, INTF; clear interrupt  
! flag
```

```
retfie; → return from interrupt
```

```
end
```

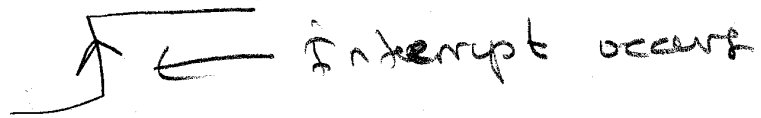
5

OPTION Registers

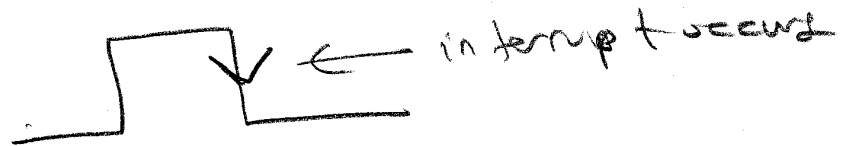


↓ Interrupt Edge Select Bit

1 = Interrupt on rising edge
of RBO / INT pin



0 = Interrupt on falling edge
of RBO / INT pin



When an interrupt occurs, the program execution continues with interrupt subroutine. To disable new interrupts while the executing the interrupt Subroutine INTE should be reset.

↓ bcf INTCON, INTE
and interrupt flag should also be cleared inside interrupt subroutine.

⑥

During an interrupt if the content of W register and STATUS register is to be protected then the interrupt subroutine should be written as follows..

```
org 0x004;  
goto interrupt-subroutine
```

```
interrupt-subroutine
```

```
movwf Temp-W;  
swpf STATUS, W;  
movwf Temp-S;
```

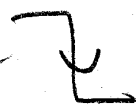
```
swpf Temp-W  
movwf STATUS,  
swpf Temp-W, F;  
swpf Temp-W, W  
retfie;
```

movwf → changes the zero flag in STATUS register, here swpf is used to save register contents.

(7)

Exo

write a program such that

when a falling pulse  at RB0 INT

occurs

RBL is turned ON.

S/n: